

COMMON FIXED POINT THEOREMS IN G-METRIC SPACES WITH Ω-DISTANCE

ISSAM ABU-IRWAQ, INAM NUSEIR, ANWAR BATAIHAH

ABSTRACT. In this paper we prove some common fixed point theorems for self mappings of cyclic form using the concept of generalized Ω -distance mappings that was introduced by K. Abodaya *et.al.* [1] in a complete G_b -metric space in sense of A. Aghanjani *et.al.* [2].

1. INTRODUCTION AND PRELIMINARY

In 1989, Bakhtin [3] introduced the concept of b-metric spaces as a generalization of the usual concept of metric spaces, while the result of Bakhtin became known more by Czerwinski [4]. In 2006 Z. Mustafa and B. Sims [5] generalized metric spaces in a different way and called this generalization a G-metric space. After that many authors studied many fixed and common fixed point results in G-metric spaces, see [7]–[36]. In 2010 R. Saadati *et.al.* [15] introduced the concept of Ω -distance as a generalization of ω -distance [16] and proved some of the fixed point results. Then after, many fixed point results were studied using Ω -distance mappings, see [17]–[21].

On the other hand, A. Aghanjani *et.al.* [2] used the concept of G-metric spaces and the concept of b-metric spaces introduced the concept of G_b -metric spaces.

Recently, many authors proved many fixed and common fixed point theorems for mappings of cyclic form in different metric spaces, see [22]–[36].

The concept of G_b -metric spaces is defined as follows:

Definition 1.1. [2] Let X be a nonempty set and $s \geq 1$ be a given real number. Suppose that a mapping $G : X \times X \times X \rightarrow \mathbb{R}^+$ is a function satisfies:

$$(G_b1) \quad G(x, y, z) = 0 \text{ if } x = y = z;$$

$$(G_b2) \quad G(x, x, y) > 0 \text{ for all } x, y \in X, \text{ with } x \neq y;$$

$$(G_b3) \quad G(x, y, y) \leq G(x, y, z) \text{ for all } x, y, z \in X, \text{ with } y \neq z;$$

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(G_b 4) $G(x, y, z) = G(p\{x, y, z\})$, where p is a permutation of x, y, z (symmetry);

(G_b 5) $G(x, y, z) \leq s[G(x, a, a) + G(a, y, z)] \forall x, y, z, a \in X$ (rectangle inequality).

The function G is called a generalized b -metric and the pair (X, G) is called generalized b -metric space or G_b -metric space.

It is clear that the class of G_b -metric spaces is larger than the G-metric spaces.

Example 1.1. [2] Let (X, G) be a G-metric space, and $G_*(x, y, z) = G(x, y, z)^p$, where $p > 1$ is a real number.

Aghanjani et.al. defined the G_b -convergence and G_b -Cauchy sequences as follows:

Definition 1.2. [2] Let X be a G_b -metric space. A sequence (x_n) in X is said to be

(1) G_b -convergent to $x \in X$ if for any $\epsilon > 0$, there exists $k \in \mathbb{N}$ such that for all $n, m \geq k$, $G(x, x_n, x_m) < \epsilon$.

(2) G_b -Cauchy sequence if for any $\epsilon > 0$, there exists $k \in \mathbb{N}$ such that for all $n, m, l \geq k$, $G(x_n, x_m, x_l) < \epsilon$.

Proposition 1.1. [2] Let X be a G_b -metric space. Then the following are equivalent:

- (1) the sequence (x_n) is G_b -convergent to x .
- (2) $G(x_n, x_n, x) \rightarrow 0$ as $n \rightarrow \infty$.
- (3) $G(x_n, x, x) \rightarrow 0$ as $n \rightarrow \infty$.

Proposition 1.2. [2] Let X be a G_b -metric space. Then the following are equivalent:

- (1) the sequence (x_n) is G_b -Cauchy .
- (2) for any $\epsilon > 0$, there exists $k \in \mathbb{N}$ such that for all $n, m \geq k$, $G(x_n, x_m, x_m) < \epsilon$.

Definition 1.3. A G_b -metric space X is called G_b -complete or complete G_b -metric space if every G_b -Cauchy sequence is G_b -convergent in X .

Definition 1.4. [1] Let X be a G_b -metric space. Then a mapping $\Omega : X \times X \times X \rightarrow [0, \infty)$ is called a generalized Ω -distance mapping or Ω_b -distance mapping on X if the following conditions satisfied:

- (1) $\Omega(x, y, z) \leq s [\Omega(x, a, a) + \Omega(a, y, z)] \forall x, y, z, a \in X$ and $s \geq 1$,
- (2) for any $x, y \in X$, $\Omega(x, y, .), \Omega(x, ., y) : X \rightarrow X$ are lower semi continuous,
- (3) for every $\epsilon > 0$, there is a $\delta > 0$ such that $\Omega(x, a, a) \leq \delta$ and $\Omega(a, y, z) \leq \delta$ imply $G_b(x, y, z) \leq \epsilon$.

Example 1.2. [1] Let $X = \mathbb{R}$ and Consider the G_b -metric G defined by $G(x, y, z) = (|x-y| + |y-z| + |x-z|)^2 \forall x, y, z \in \mathbb{R}$. Define $\Omega : X \times X \times X \rightarrow [0, \infty)$ by $\Omega(x, y, z) = (|x-y| + |x-z|)^2 \forall x, y, z \in \mathbb{R}$. Then Ω is a generalized Ω -distance with $s = 2$.

Definition 1.5. [1] Let (X, G) be a G_b -metric space and Ω be an Ω_b -distance on X . Then we say that X is Ω -bounded if there exists $M > 0$ such that $\Omega(x, y, z) \leq M$ for all $x, y, z \in X$.

Lemma 1.1. [1] Let X be a G_b -metric space and Ω_b be a generalized Ω -distance on X . Let $(x_n), (y_n)$ be sequences in X , $(\alpha_n), (\beta_n)$ be sequences in $[0, \infty)$ converging to zero and let $x, y, z, a \in X$. Then we have the following:

- (1) If $\Omega_b(y_n, x_n, x_n) \leq \alpha_n$ and $\Omega_b(x_n, y_m, z) \leq \beta_n$ for any $m > n \in \mathbb{N}$, then $G(y_n, y_m, z) \rightarrow 0$ and hence $y_n \rightarrow z$.
- (2) If $\Omega_b(y, x_n, x_n) \leq \alpha_n$ and $\Omega_b(x_n, y, z) \leq \beta_n$ for $n \in \mathbb{N}$, then $G(y, y, z) < \epsilon$ and hence $y = z$.
- (3) If $\Omega_b(x_n, x_m, x_l) \leq \alpha_n$ for any $m, n, l \in \mathbb{N}$ with $n \leq m \leq l$, then (x_n) is a G_b -Cauchy sequence.
- (4) If $\Omega_b(x_n, a, a) \leq \alpha_n$ for any $n \in \mathbb{N}$, then (x_n) is a G_b -Cauchy sequence.

2. MAIN RESULT

In this section, the concept of the cyclic mappings is given as follows:

Definition 2.1. Let A and B be two nonempty subsets of a space X . A mapping $T : A \cup B \rightarrow A \cup B$ is called cyclic if $T(A) \subseteq B$ and $T(B) \subseteq A$.

Now, we state and prove our main result.

Definition 2.2. Let (X, G) be a complete G_b -metric space and Ω be a generalized Ω -distance on X with a constant $s > 1$ such that X is Ω -bounded. Let A and B be two nonempty closed subsets of X with respect to the topology induced by G with $X = A \cup B$ and $A \cap B \neq \emptyset$. Two mappings $f, g : A \cup B \rightarrow A \cup B$ are said to be Ω_b -cyclic Kannan contraction if $f(A) \subseteq B$ and $g(B) \subseteq A$ and there exists $r \in [0, \frac{1}{1+s})$ such that the following conditions hold true

$$\Omega(fx, gfx, gy) \leq r [\Omega(x, fx, fx) + \Omega(y, gy, gy)] \quad \forall x \in A \text{ and } \forall y \in B, \quad (2.1)$$

$$\Omega(gx, fgx, fy) \leq r [\Omega(x, gx, gx) + \Omega(y, fy, fy)] \quad \forall y \in A \text{ and } \forall x \in B, \quad (2.2)$$

$$\Omega(fx, gfx, fy) \leq r [\Omega(x, fx, fx) + \Omega(y, fy, fy)] \quad \forall x, y \in A, \quad (2.3)$$

and

$$\Omega(gx, fgx, gy) \leq r [\Omega(x, gx, gx) + \Omega(y, gy, gy)] \quad \forall x, y \in B. \quad (2.4)$$

Theorem 2.1. Let (X, G) be a complete G_b -metric space and Ω be a generalized Ω -distance on X such that X is Ω -bounded. Let A and B be two nonempty closed subsets of X with respect to the topology induced by G with $X = A \cup B$ and $A \cap B \neq \emptyset$. Suppose that f and g are Ω_b -cyclic Kannan contraction. Also, $\forall u \in X$ if $fu \neq u$ or $gu \neq u$, then (b) $\inf\{\Omega(fx, gfx, u) : x \in X\} > 0$. If f or g is continuous, then f and g have a unique common fixed point in $A \cap B$.

Proof. Let $x_0 \in A$. Since $f(A) \subseteq B$, then $fx_0 = x_1 \in B$. Also, since $g(B) \subseteq A$, then $gx_1 = x_2 \in A$. Continuing this process we obtain a sequence (x_n) in X such that $fx_{2n} = x_{2n+1}$,

$x_{2n} \in A$, $gx_{2n+1} = x_{2n+2}$ and $x_{2n+1} \in B$, $n = 0, 1, 2, \dots$.

First, since X is Ω -bounded, then there exists $M \geq 0$ such that

$$\Omega(x, y, z) \leq M \quad \forall x, y, z \in X.$$

Now, our claim is to show that $\Omega(x_n, x_{n+1}, x_{n+s}) \leq q^{n-1} M \quad \forall n, s \in \mathbb{N}$, where $q = \frac{r}{1-r}$.

Let $n, s \in \mathbb{N}$. Then we have four cases:

Case (1): n is even and s is even. Therefore $n = 2t$ for some $t \in \mathbb{N}$. By (2.4), we have

$$\begin{aligned} \Omega(x_n, x_{n+1}, x_{n+s}) &= \Omega(x_{2t}, x_{2t+1}, x_{2t+s}) \\ &= \Omega(gx_{2t-1}, fgx_{2t-1}, gx_{2t+s-1}) \\ &\leq r [\Omega(x_{2t-1}, x_{2t}, x_{2t}) + \Omega(x_{2t+s-1}, x_{2t+s}, x_{2t+s})]. \end{aligned} \tag{2.5}$$

Also, by (2.1), we get

$$\begin{aligned} &\Omega(x_{2t-1}, x_{2t}, x_{2t}) + \Omega(x_{2t+s-1}, x_{2t+s}, x_{2t+s}) \\ &= \Omega(fx_{2t-2}, gfx_{2t-2}, gx_{2t-1}) + \Omega(fx_{2t+s-2}, gfx_{2t+s-2}, gx_{2t+s-1}) \\ &\leq r [\Omega(x_{2t-2}, x_{2t-1}, x_{2t-1}) + \Omega(x_{2t-1}, x_{2t}, x_{2t})] \\ &\quad + r [\Omega(x_{2t+s-2}, x_{2t+s-1}, x_{2t+s-1}) + \Omega(x_{2t+s-1}, x_{2t+s}, x_{2t+s})]. \end{aligned}$$

Therefore

$$\begin{aligned} &\Omega(x_{2t-1}, x_{2t}, x_{2t}) + \Omega(x_{2t+s-1}, x_{2t+s}, x_{2t+s}) \\ &\leq \frac{r}{1-r} [\Omega(x_{2t-2}, x_{2t-1}, x_{2t-1}) + \Omega(x_{2t+s-2}, x_{2t+s-1}, x_{2t+s-1})] \\ &\leq q [\Omega(x_{2t-2}, x_{2t-1}, x_{2t-1}) + \Omega(x_{2t+s-2}, x_{2t+s-1}, x_{2t+s-1})]. \end{aligned}$$

Hence by applying the previous steps repeatedly we get

$$\Omega(x_{2t-1}, x_{2t}, x_{2t}) + \Omega(x_{2t+s-1}, x_{2t+s}, x_{2t+s}) \leq q^{n-1} [\Omega(x_0, x_1, x_1) + \Omega(x_s, x_{s+1}, x_{s+1})].$$

Since X in Ω -bounded, then $\Omega(x_{2t-1}, x_{2t}, x_{2t}) + \Omega(x_{2t+s-1}, x_{2t+s}, x_{2t+s}) \leq 2q^{n-1}M$.

Since $r < \frac{1}{2}$, then inequality (2.5) becomes

$$\Omega(x_n, x_{n+1}, x_{n+s}) \leq q^{n-1} M. \tag{2.6}$$

Case (2): n is odd, s is even. Therefore $n=2t+1$ for some $t \in \mathbb{N} \cup \{0\}$. By (2.3), we get

$$\begin{aligned} \Omega(x_n, x_{n+1}, x_{n+s}) &= \Omega(x_{2t+1}, x_{2t+2}, x_{2t+s+1}) \\ &= \Omega(fx_{2t}, gfx_{2t}, fx_{2t+s}) \\ &\leq r [\Omega(x_{2t}, x_{2t+1}, x_{2t+1}) + \Omega(x_{2t+s}, x_{2t+s+1}, x_{2t+s+1})]. \end{aligned} \tag{2.7}$$

By (2.2), we get

$$\begin{aligned}
& \Omega(x_{2t}, x_{2t+1}, x_{2t+1}) + \Omega(x_{2t+s}, x_{2t+s+1}, x_{2t+s+1}) \\
&= \Omega(gx_{2t-1}, fgx_{2t-1}, fx_{2t}) + \Omega(gx_{2t+s-1}, fgx_{2t+s-1}, fx_{2t+s}) \\
&\leq r [\Omega(x_{2t-1}, x_{2t}, x_{2t}) + \Omega(x_{2t}, x_{2t+1}, x_{2t+1})] \\
&+ r [\Omega(x_{2t+s-1}, x_{2t+s}, x_{2t+s}) + \Omega(x_{2t+s}, x_{2t+s+1}, x_{2t+s+1})].
\end{aligned}$$

Therefore

$$\begin{aligned}
& \Omega(x_{2t}, x_{2t+1}, x_{2t+1}) + \Omega(x_{2t+s}, x_{2t+s+1}, x_{2t+s+1}) \\
&\leq \frac{r}{1-r} [\Omega(x_{2t-1}, x_{2t}, x_{2t}) + \Omega(x_{2t+s-1}, x_{2t+s}, x_{2t+s})] \\
&\leq q [\Omega(x_{2t-1}, x_{2t}, x_{2t}) + \Omega(x_{2t+s-1}, x_{2t+s}, x_{2t+s})].
\end{aligned}$$

Hence by applying the previous steps repeatedly we get

$$\Omega(x_{2t}, x_{2t+1}, x_{2t+1}) + \Omega(x_{2t+s}, x_{2t+s+1}, x_{2t+s+1}) \leq q^{n-1} [\Omega(x_0, x_1, x_1) + \Omega(x_s, x_{s+1}, x_{s+1})].$$

Since X in Ω -bounded then $\Omega(x_{2t}, x_{2t+1}, x_{2t+1}) + \Omega(x_{2t+s}, x_{2t+s+1}, x_{2t+s+1}) \leq 2q^{n-1}M$.

Since $r < \frac{1}{2}$, then inequality (2.7) becomes

$$\Omega(x_n, x_{n+1}, x_{n+s}) \leq q^{n-1}M. \quad (2.8)$$

Case (3): n is even, and s is odd. Therefore $n = 2t$ for some $t \in \mathbb{N}$. By (2.2), we have

$$\begin{aligned}
\Omega(x_n, x_{n+1}, x_{n+s}) &= \Omega(x_{2t}, x_{2t+1}, x_{2t+s}) \\
&= \Omega(gx_{2t-1}, fgx_{2t-1}, fx_{2t+s-1}) \\
&\leq r [\Omega(x_{2t-1}, x_{2t}, x_{2t}) + \Omega(x_{2t+s-1}, x_{2t+s}, x_{2t+s})].
\end{aligned} \quad (2.9)$$

By (2.1) and (2.2), we have

$$\begin{aligned}
& \Omega(x_{2t-1}, x_{2t}, x_{2t}) + \Omega(x_{2t+s-1}, x_{2t+s}, x_{2t+s}) \\
&= \Omega(fx_{2t-2}, gfx_{2t-2}, gx_{2t-1}) + \Omega(gx_{2t+s-2}, fgx_{2t+s-2}, fx_{2t+s-1}) \\
&\leq r [\Omega(x_{2t-2}, x_{2t-1}, x_{2t-1}) + \Omega(x_{2t-1}, x_{2t}, x_{2t})] \\
&+ r [\Omega(x_{2t+s-2}, x_{2t+s-1}, x_{2t+s-1}) + \Omega(x_{2t+s-1}, x_{2t+s}, x_{2t+s})].
\end{aligned}$$

Therefore

$$\begin{aligned}
& \Omega(x_{2t-1}, x_{2t}, x_{2t}) + \Omega(x_{2t+s-1}, x_{2t+s}, x_{2t+s}) \\
&\leq \frac{r}{1-r} [\Omega(x_{2t-2}, x_{2t-1}, x_{2t-1}) + \Omega(x_{2t+s-2}, x_{2t+s-1}, x_{2t+s-1})] \\
&\leq q [\Omega(x_{2t-2}, x_{2t-1}, x_{2t-1}) + \Omega(x_{2t+s-2}, x_{2t+s-1}, x_{2t+s-1})].
\end{aligned}$$

Hence by applying the previous steps repeatedly we get

$$\Omega(x_{2t-1}, x_{2t}, x_{2t}) + \Omega(x_{2t+s-1}, x_{2t+s}, x_{2t+s}) \leq q^{n-1} [\Omega(x_0, x_1, x_1) + \Omega(x_s, x_{s+1}, x_{s+1})]$$

Since X in Ω -bounded, then $\Omega(x_{2t-1}, x_{2t}, x_{2t}) + \Omega(x_{2t+s-1}, x_{2t+s}, x_{2t+s}) \leq 2q^{n-1}M$.

Since $r < \frac{1}{2}$, then inequality (2.9) becomes

$$\Omega(x_n, x_{n+1}, x_{n+s}) \leq q^{n-1}M. \quad (2.10)$$

Case (4): n is odd, s is odd. Therefore $n=2t+1$ for some $t \in \mathbb{N} \cup \{0\}$. By (2.1), we get

$$\begin{aligned} \Omega(x_n, x_{n+1}, x_{n+s}) &= \Omega(x_{2t+1}, x_{2t+2}, x_{2t+s+1}) \\ &= \Omega(fx_{2t}, gfx_{2t}, gx_{2t+s}) \\ &\leq r [\Omega(x_{2t}, x_{2t+1}, x_{2t+1}) + \Omega(x_{2t+s}, x_{2t+s+1}, x_{2t+s+1})]. \end{aligned} \quad (2.11)$$

By (2.1) and (2.2), we have

$$\begin{aligned} &\Omega(x_{2t}, x_{2t+1}, x_{2t+1}) + \Omega(x_{2t+s}, x_{2t+s+1}, x_{2t+s+1}) \\ &= \Omega(gx_{2t-1}, fgx_{2t-1}, fx_{2t}) + \Omega(fx_{2t+s-1}, gfx_{2t+s-1}, gx_{2t+s}) \\ &\leq r [\Omega(x_{2t-1}, x_{2t}, x_{2t}) + \Omega(x_{2t}, x_{2t+1}, x_{2t+1})] \\ &\quad + r [\Omega(x_{2t+s-1}, x_{2t+s}, x_{2t+s}) + \Omega(x_{2t+s}, x_{2t+s+1}, x_{2t+s+1})]. \end{aligned}$$

So

$$\begin{aligned} &\Omega(x_{2t}, x_{2t+1}, x_{2t+1}) + \Omega(x_{2t+s}, x_{2t+s+1}, x_{2t+s+1}) \\ &\leq \frac{r}{1-r} [\Omega(x_{2t-1}, x_{2t}, x_{2t}) + \Omega(x_{2t+s-1}, x_{2t+s}, x_{2t+s})] \\ &\leq q [\Omega(x_{2t-1}, x_{2t}, x_{2t}) + \Omega(x_{2t+s-1}, x_{2t+s}, x_{2t+s})]. \end{aligned}$$

Hence by applying the previous steps repeatedly we get

$$\Omega(x_{2t}, x_{2t+1}, x_{2t+1}) + \Omega(x_{2t+s}, x_{2t+s+1}, x_{2t+s+1}) \leq q^{n-1} [\Omega(x_0, x_1, x_1) + \Omega(x_s, x_{s+1}, x_{s+1})].$$

Since X in Ω -bounded then $\Omega(x_{2t}, x_{2t+1}, x_{2t+1}) + \Omega(x_{2t+s}, x_{2t+s+1}, x_{2t+s+1}) \leq 2q^{n-1}M$.

Since $r < \frac{1}{2}$, then inequality (2.11) becomes

$$\Omega(x_n, x_{n+1}, x_{n+s}) \leq q^{n-1}M. \quad (2.12)$$

Thus in all cases we have

$$\Omega(x_n, x_{n+1}, x_{n+s}) \leq q^{n-1}M, \forall n, s \in \mathbb{N}. \quad (2.13)$$

Now, $\forall l \geq m \geq n$, we have

$$\begin{aligned}
\Omega(x_n, x_m, x_l) &\leq s\Omega(x_n, x_{n+1}, x_{n+1}) + s\Omega(x_{n+1}, x_m, x_l) \\
&\leq s\Omega(x_n, x_{n+1}, x_{n+1}) + s^2\Omega(x_{n+1}, x_{n+2}, x_{n+2}) + s^2\Omega(x_{n+2}, x_m, x_l) \\
&\vdots \\
&\leq s\Omega(x_n, x_{n+1}, x_{n+1}) + s^2\Omega(x_{n+1}, x_{n+2}, x_{n+2}) + \cdots \\
&+ s^{m-n-1}\Omega(x_{m-2}, x_{m-1}, x_{m-1}) + s^{m-n-1}\Omega(x_{m-1}, x_m, x_l) \\
&\leq sq^{n-1}M + s^2q^nM + \cdots + s^{m-n-1}q^{m-3}M + s^{m-n-1}q^{m-2}M \\
&\leq sq^{n-1}M + s^2q^nM + s^3q^{n+1}M + \cdots \\
&= sq^{n-1}M(1 + sq + (sq)^2 + \cdots) \\
&= sq^{n-1}M \frac{1}{1-sq}.
\end{aligned}$$

Thus by Lemma (1.1) (x_n) is a G_b -Cauchy sequence. Therefore there exists $u \in X$ such that (x_n) is G -convergent to u . Since (x_n) G_b -converges to u , then each subsequence of (x_n) also G_b -converges to u . So the subsequences $(x_{2n+1}) = (fx_{2n})$ and $(x_{2n+2}) = (gx_{2n+1})$ are G_b -converge to u .

First, (without lose of generality) suppose that f is continuous. Then $\lim_{n \rightarrow \infty} fx_{2n} = fu$ and $\lim_{n \rightarrow \infty} x_{2n+1} = u$, by uniqueness of the limit we have $fu = u$.

Let $\epsilon > 0$. By the lower semi continuity of Ω , we have

$$\Omega(x_n, x_m, u) \leq \liminf_{p \rightarrow \infty} \Omega(x_n, x_m, x_p) \leq \epsilon, \forall m \geq n.$$

Suppose that $gu \neq u$. Then by (b), we get

$$\begin{aligned}
0 &< \inf\{\Omega(fx, gfx, u) : x \in X\} \\
&\leq \inf\{\Omega(x_n, x_{n+1}, u) : n \text{ odd}\} \leq \epsilon
\end{aligned}$$

for each $\epsilon > 0$ a contradiction. Hence $u = gu$.

Since $(x_{2n}) \subseteq A$ and A is closed, then $u \in A$. Also, since $(x_{2n+1}) \subseteq B$ and B is closed, then $u \in B$. Hence u is a common fixed point for f and g in $A \cap B$.

Now, we prove the uniqueness. First, we show that if $w = fw = gw$, then $\Omega(w, w, w) = 0$.

By (2.1), we have

$$\begin{aligned}
\Omega(w, w, w) = \Omega(fw, gfw, gw) &\leq r[\Omega(w, w, w) + \Omega(w, w, w)] \\
&\leq 2r\Omega(w, w, w).
\end{aligned}$$

Since $r < \frac{1}{2}$, then $\Omega(w, w, w) = 0$.

Now, let $v \in X$ be another common fixed point for f and g . Then by (2.1), we get

$\Omega(v, v, u) = \Omega(fv, gv, gu) \leq r[\Omega(v, v, v) + \Omega(u, u, u)]$. Since $v = fv = gv$ and $u = fu = gu$, then $\Omega(v, v, v) = \Omega(u, u, u) = 0$. Therefore $\Omega(v, v, u) = 0$. Thus by the definition of Ω -distance we have $G(v, v, u) = 0$. Hence $u = v$. \square

If we choose $X = A = B$ in Theorem (2.1), then we have the following result

Corollary 2.1. Let (X, G) be a complete G_b -metric space and Ω be a generalized Ω -distance on X with constant $s > 1$ such that X is Ω -bounded. Suppose that $f, g : X \rightarrow X$ be two self mappings. Also, assume that there exists $r \in [0, \frac{1}{1+s})$ such that the following conditions hold true:

$$\Omega(fx, gfx, gy) \leq r [\Omega(x, fx, fx) + \Omega(y, gy, gy)] \quad \forall x, y \in X, \quad (2.14)$$

$$\Omega(gx, fgx, fy) \leq r [\Omega(x, gx, gx) + \Omega(y, fy, fy)] \quad \forall x, y \in X, \quad (2.15)$$

$$\Omega(fx, gfx, fy) \leq r [\Omega(x, fx, fx) + \Omega(y, fy, fy)] \quad \forall x, y \in X, \quad (2.16)$$

and

$$\Omega(gx, fgx, gy) \leq r [\Omega(x, gx, gx) + \Omega(y, gy, gy)] \quad \forall x, y \in X. \quad (2.17)$$

Also, $\forall u \in X$ if $fu \neq u$ or $gu \neq u$, then (b) $\inf\{\Omega(fx, gfx, u) : x \in X\} > 0$.

If f or g is continuous, then f and g have a unique common fixed point in X .

If we replace g by f in Theorem (2.1), then condition (b) can be dropped. So we have the following theorem

Theorem 2.2. Let (X, G) be a complete G_b -metric space and Ω be a generalized Ω -distance on X with constant $s > 1$ such that X is Ω -bounded. Let A and B be two nonempty closed subsets of X with respect to the topology induced by G with $X = A \cup B$ and $A \cap B \neq \emptyset$. Suppose that $f : A \cup B \rightarrow A \cup B$ be a cyclic mapping. Also, assume that there exists $r \in [0, \frac{1}{1+s})$ such that the following conditions hold true

$$\Omega(fx, f^2x, fy) \leq r [\Omega(x, fx, fx) + \Omega(y, fy, fy)] \quad \forall x \in A \text{ and } \forall y \in B, \quad (2.18)$$

$$\Omega(fx, f^2x, fy) \leq r [\Omega(x, fx, fx) + \Omega(y, fy, fy)] \quad \forall y \in A \text{ and } \forall x \in B, \quad (2.19)$$

$$\Omega(fx, f^2x, fy) \leq r [\Omega(x, fx, fx) + \Omega(y, fy, fy)] \quad \forall x, y \in A, \quad (2.20)$$

and

$$\Omega(fx, f^2x, fy) \leq r [\Omega(x, fx, fx) + \Omega(y, fy, fy)] \quad \forall x, y \in B. \quad (2.21)$$

If f is continuous, then f has a unique fixed point in $A \cap B$.

Proof. By following the proof of Theorem (2.1) step by step, we get the result. \square

By choosing $X = A = B$ in Theorem (2.2), we get the following result

Corollary 2.2. Let (X, G) be a complete G_b -metric space and Ω be a generalized Ω -distance on X with constant $s > 1$ such that X is Ω -bounded. Let $f : X \rightarrow X$ be a self mapping. Also, assume that there exists $r \in [0, \frac{1}{1+s})$ such that the following condition holds true:

$$\Omega(fx, f^2x, fy) \leq r [\Omega(x, fx, fx) + \Omega(y, fy, fy)] \quad \forall x, y \in X. \quad (2.22)$$

If f is continuous, then f has a unique fixed point in X .

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ISSAM ABU-IRWAQ

JORDAN UNIVERSITY OF SCIENCE AND TECHNOLOGY, DEPARTMENT OF MATHEMATICS AND STATISTICS, IRBID 22110,
JORDAN

E-mail address: imabuirwaq@just.edu.jo

INAM NUSEIR

JORDAN UNIVERSITY OF SCIENCE AND TECHNOLOGY, DEPARTMENT OF MATHEMATICS AND STATISTICS, IRBID 22110,
JORDAN

E-mail address: imnuseir@just.edu.jo

ANWAR BATAIHAB

THE UNIVERSITY OF JORDAN, DEPARTMENT OF MATHEMATICS AMMAN, JORDAN

E-mail address: anwerbataihah@gmail.com